

Gabriel: Towards Wearable Cognitive Assistance



Kiryong Ha, **Zhuo Chen**, Wenlu Hu, Wolfgang Richter,
Padmanabhan Pillai, and Mahadev Satyanarayanan

Carnegie Mellon University



Cognitive Decline

survivors of stroke

mild cognitive impairment



Faces



Text



Daily Routine

Can Wearable Technology Help?

Continuously capture, interpret, and give guidance



System Architecture



*"Barack is saying
hello to you"*



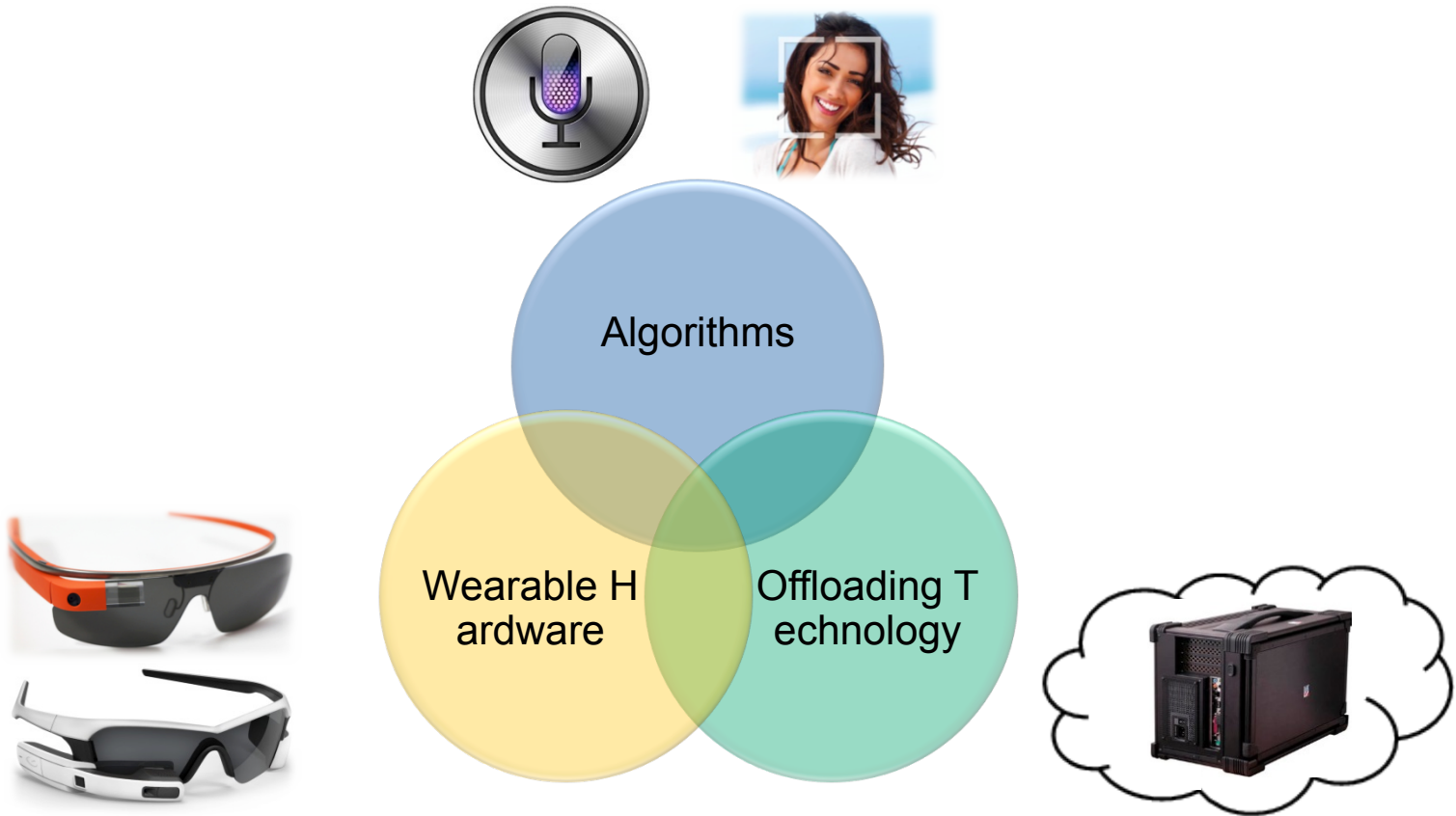
*"Please stop and
check traffic"*



*"Your dog wants to
go out for a walk"*

Why Today?

Advances in 3 Independent Arenas

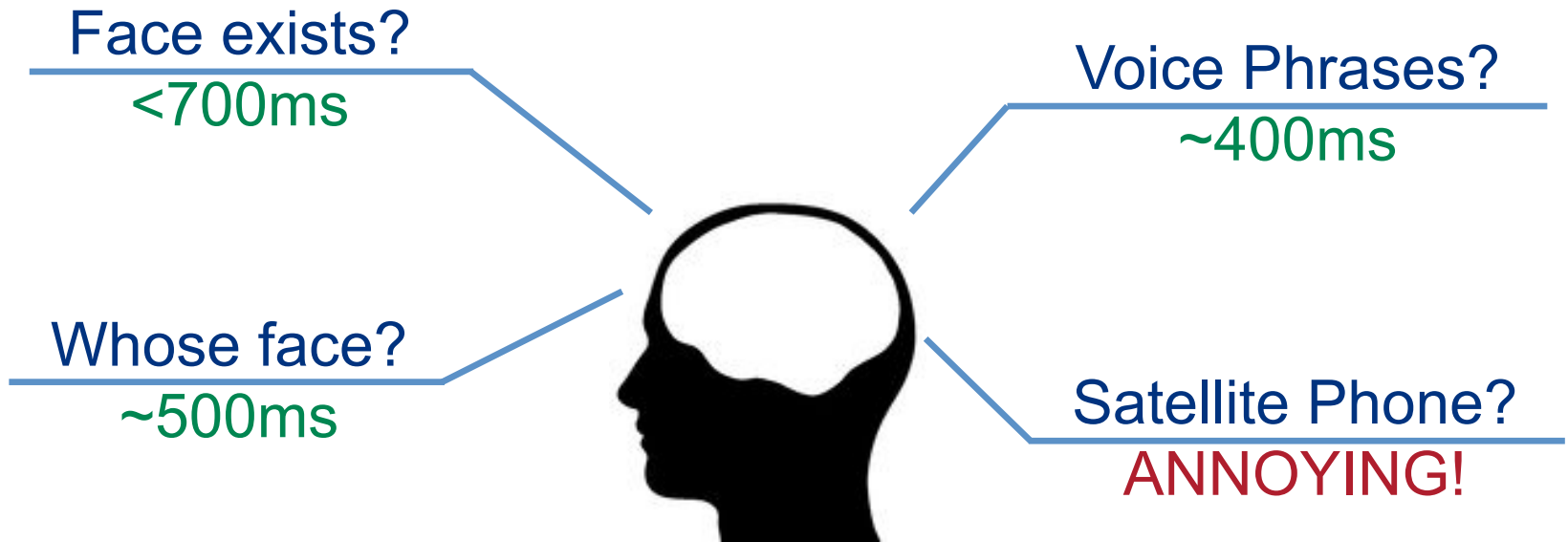


Challenges – Architecture

1. Crisp Interactive Response
2. Graceful Degradation of Services
3. Coarse-grain Parallelism

C1. Crisp Interactive Response

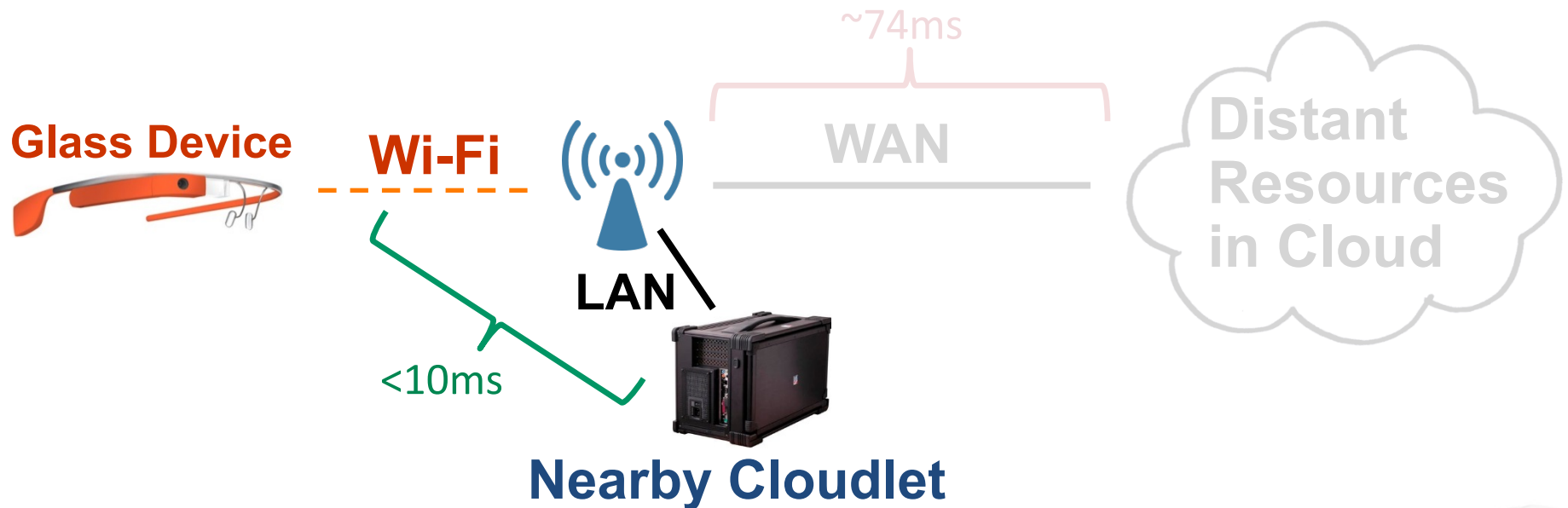
Humans are fast and sensitive



Goal: Latency of infrastructure = tens of millisecond

S1. Crisp Interactive Response

- ✗ Choice 1: standalone apps
- ✗ Choice 2: offload to cloud
- ✓ Choice 3: offload to cloudlets



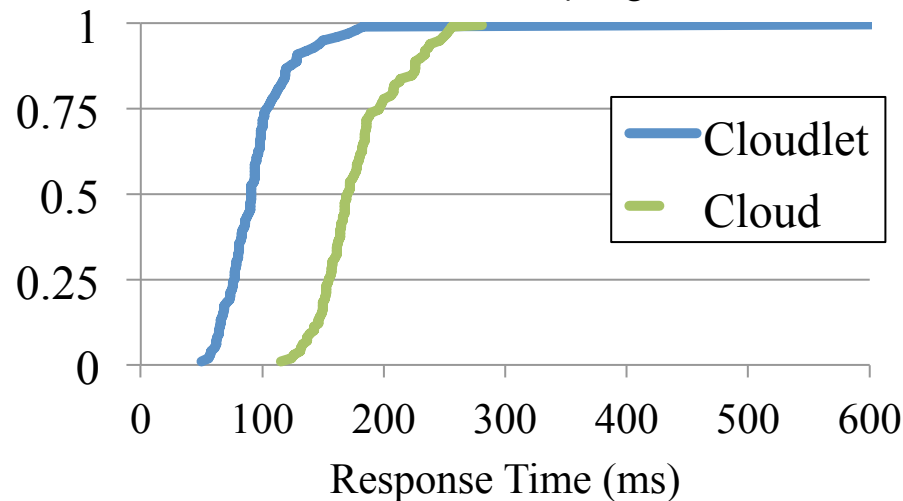
Exp. – Cloudlet Shortens Latency

Offloading vs. Standalone (OCR)

Offloading saves
latency and energy

Metric	Standalone	With Offload
Per-image speed (s)	10.49	1.28
Per-image energy(J)	12.84	1.14

Cloudlet vs. Cloud (Augmented Reality)



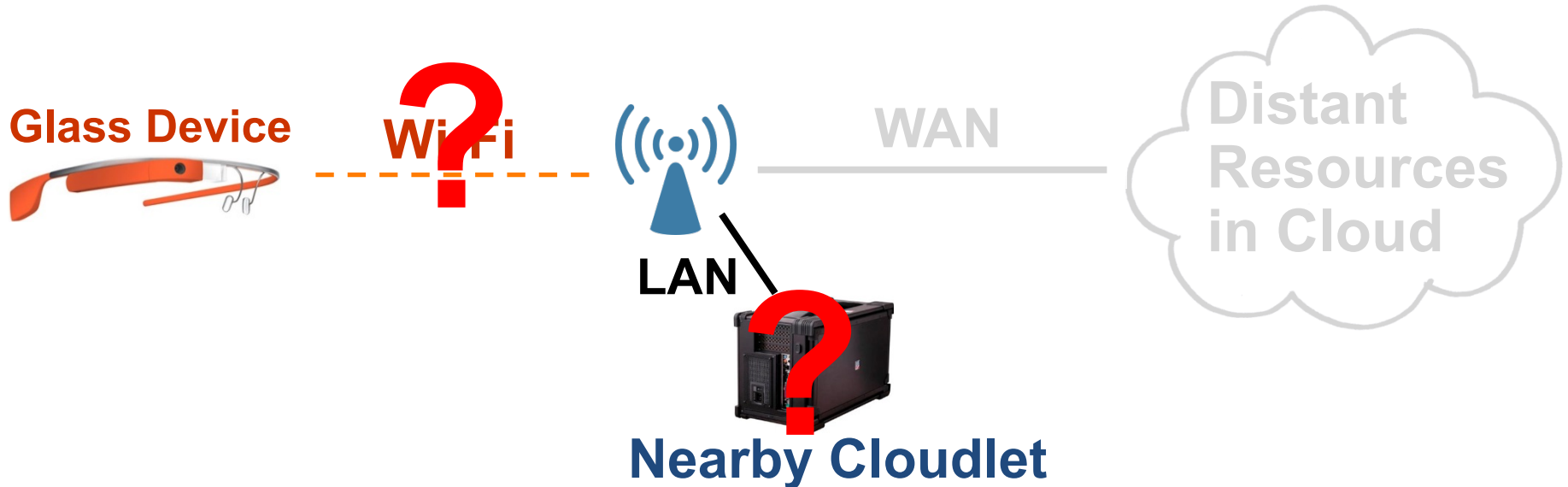
Cloudlet shortens
response time

C2. Graceful Degradation of Services

What if offloading impossible?

Situation 1: No cloudlet

Situation 2: No network



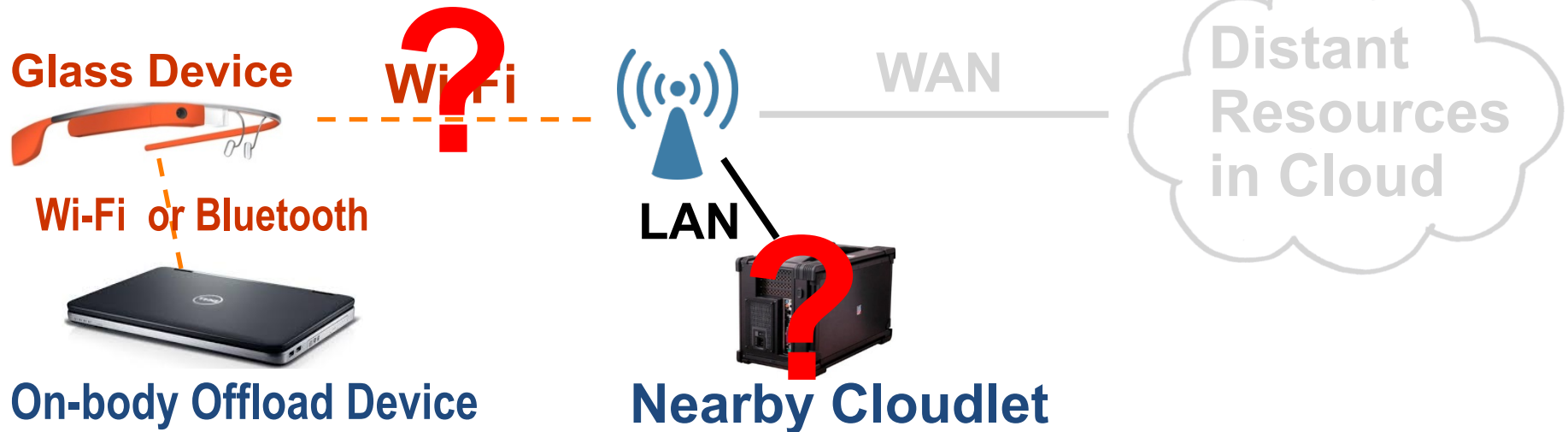
Goal: still work during failures – with performance drop

S2. Graceful Degradation of Services

Use fallback resources

No cloudlet

No network



Application-specific fidelity vs. Crispness & battery life

C3. Coarse-grain Parallelism

Don't reinvent the wheel

Face recognition
Object detection
Activity inference
OCR



Goal: reuse existing work, but...

- Programming languages are different

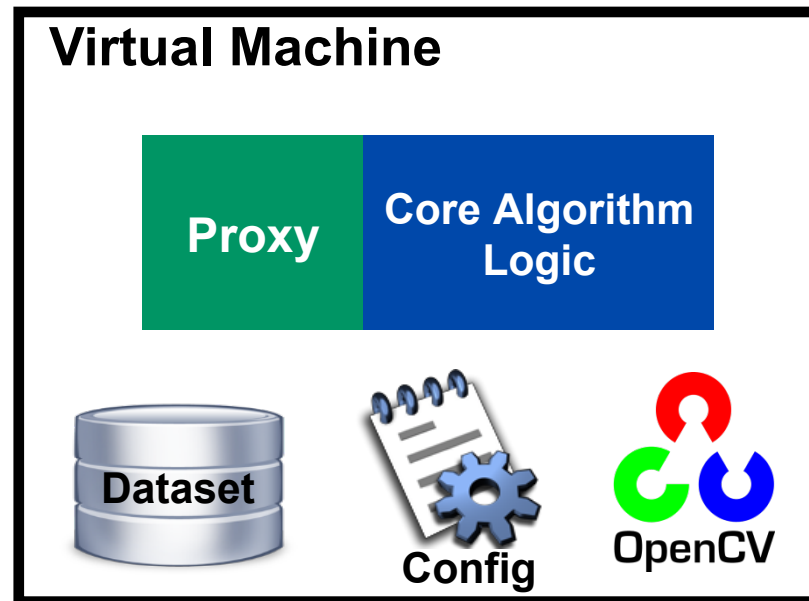


- Runtime systems are different (different OSes, closed-source, etc.)



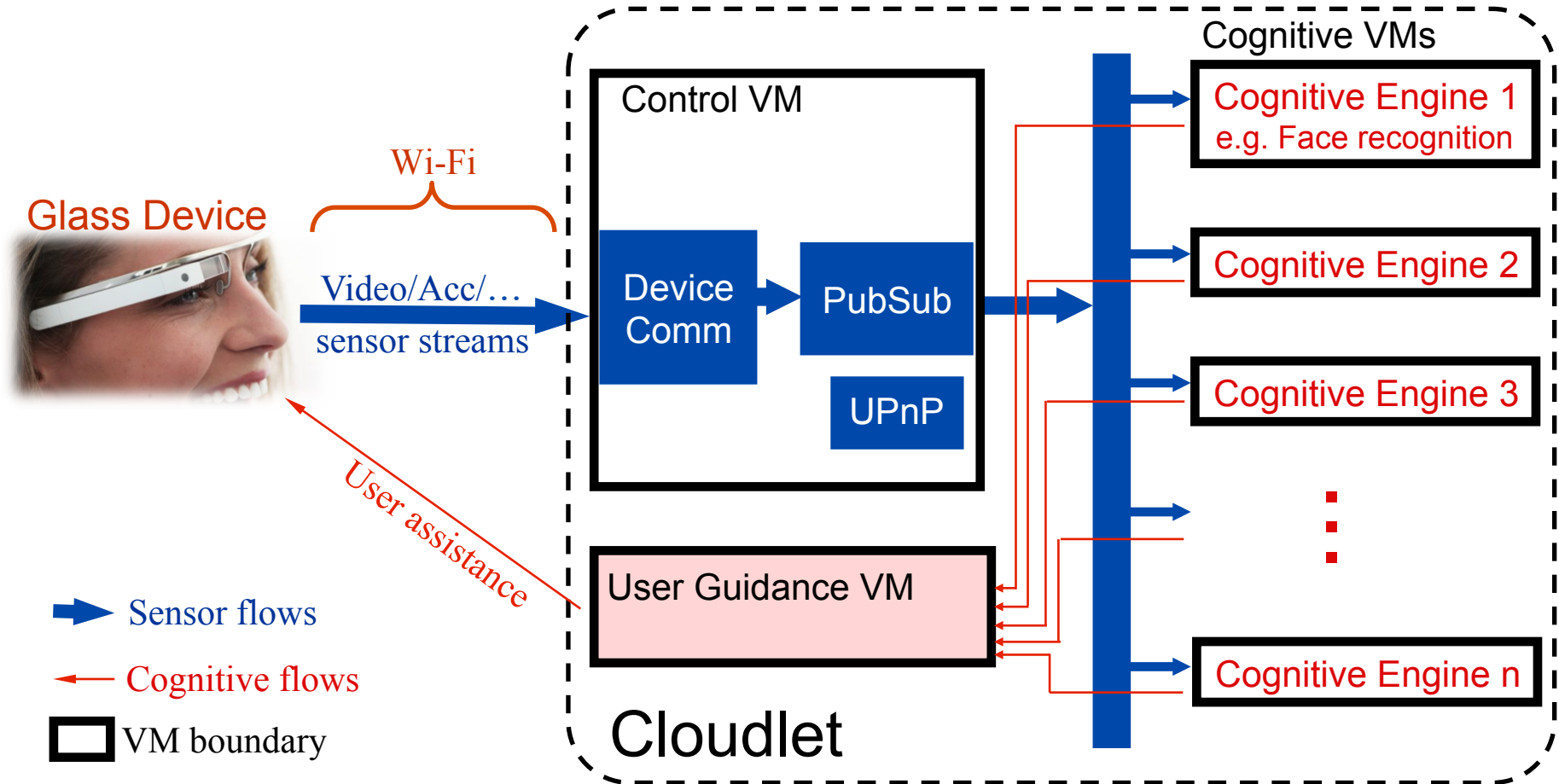
S3. Coarse-grain Parallelism

VM Ensemble and PubSub Backbone



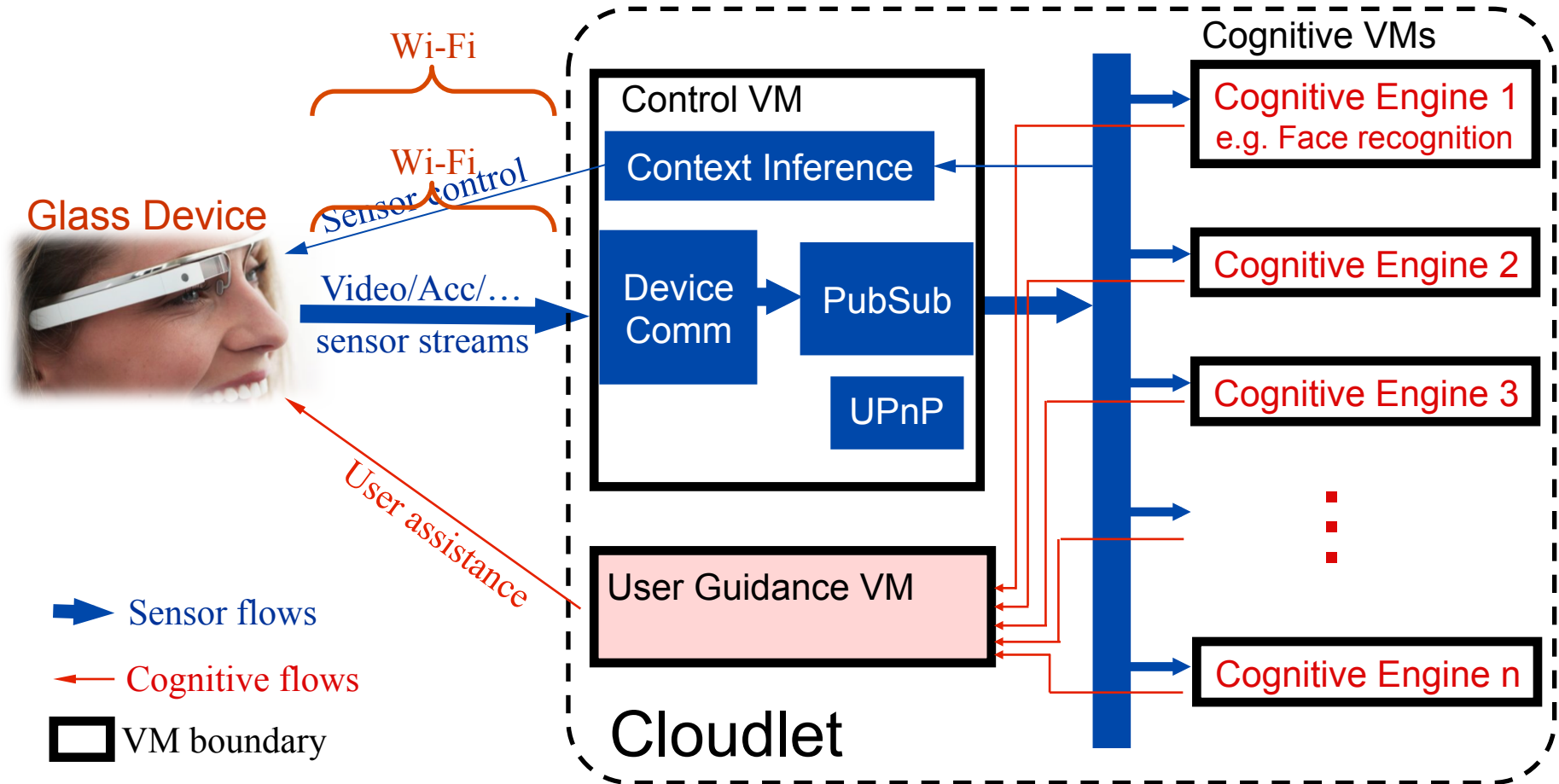
S3. Coarse-grain Parallelism

VM Ensemble and PubSub Backbone



S3. Coarse-grain Parallelism

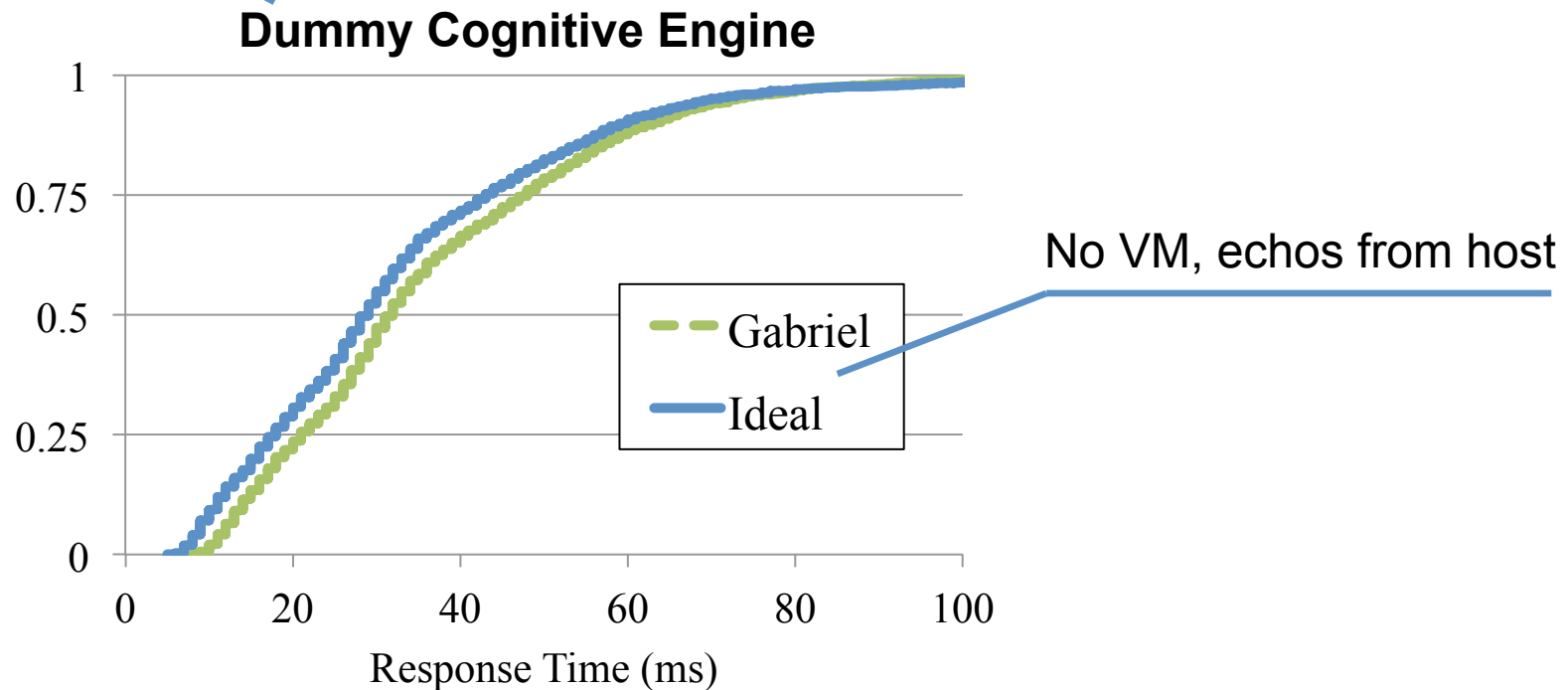
VM Ensemble and PubSub Backbone

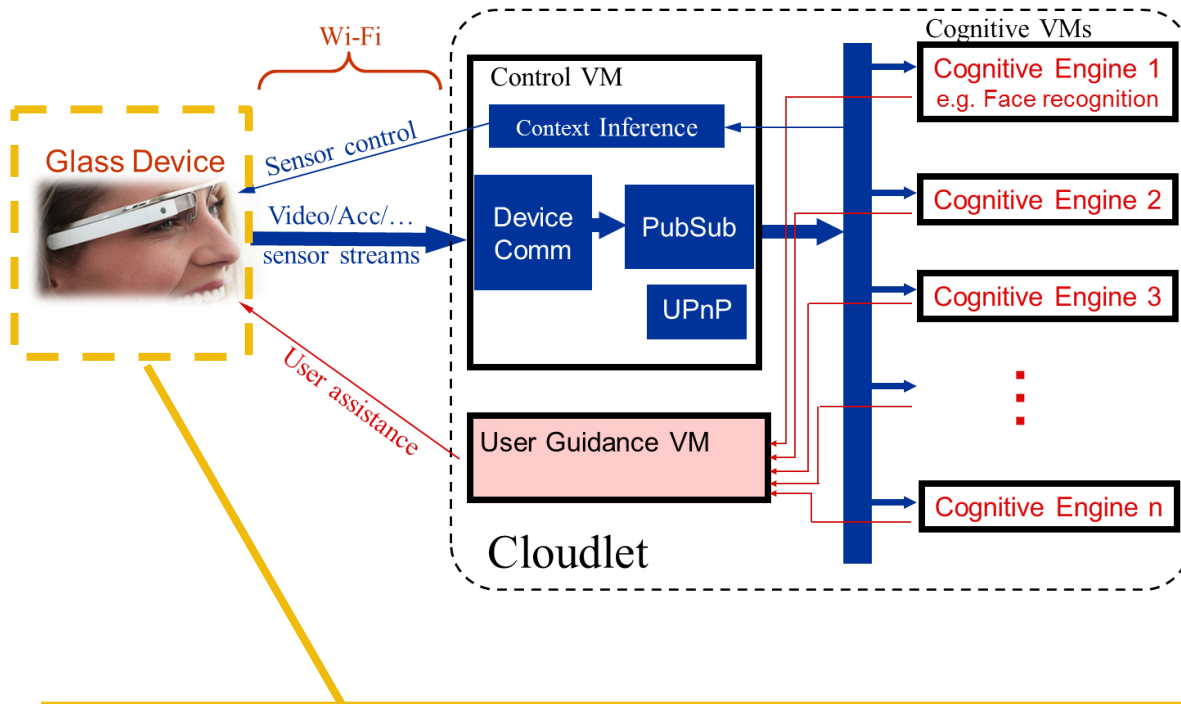


Exp. – Gabriel Overhead

Gabriel Latency: ~50ms
Gabriel Overhead: ~3ms

Echos every image





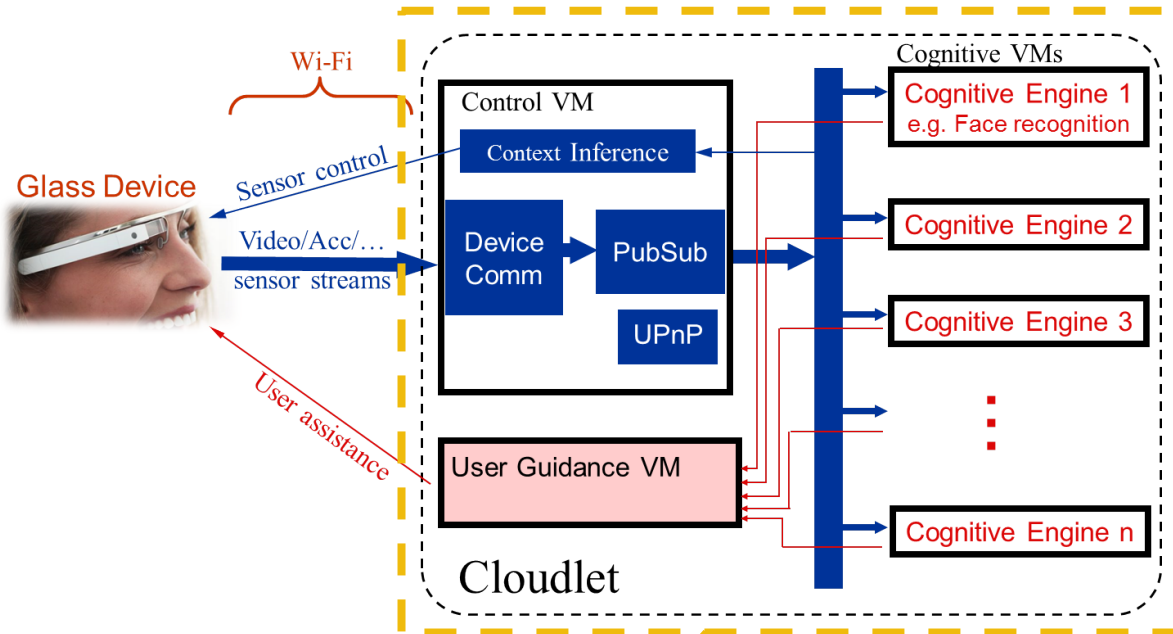
Prototype

Back-end Server

GDK Preview
TCP Connection
Speech Guidance



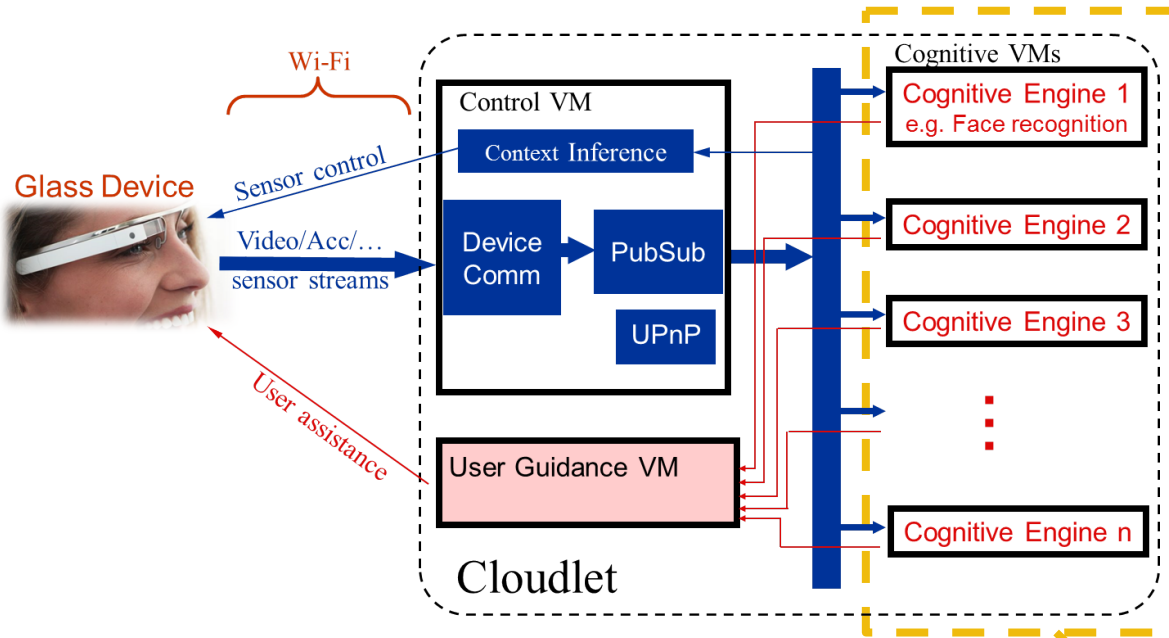
Ice pack to cool down Glass



Prototype

Back-end Server

Cloudlet: 4 advanced desktop machines
Running OpenStack – Virtualized Cloud Computing Platform



Prototype

Cognitive Engines



Face Recognition
Object Recognition (1. MOPED 2. STF)
OCR (1. Tesseract 2. VeryPDF)
Motion Classifier
Augmented Reality
Activity Detection

Commercial Product

Based on Accelerometer

Exp. – Full System Performance

Cognitive Engines are slower

Cognitive Engine	FPS	Response time (ms)					Glass Life
		1%	10%	50%	90%	99%	
Face Recognition	4.4	196	389	659	929	1175	~1 hour
Object (MOPED)	1.6	877	962	1207	1647	2118	
Object (STF)	0.4	4202	4371	4609	5055	5684	
OCR (Open)	14.4	29	41	87	147	511	
OCR (Comm)	2.3	394	435	522	653	1021	
Motion Classifier	14.0	126	152	199	260	649	
Augmented Reality	14.1	48	72	126	192	498	

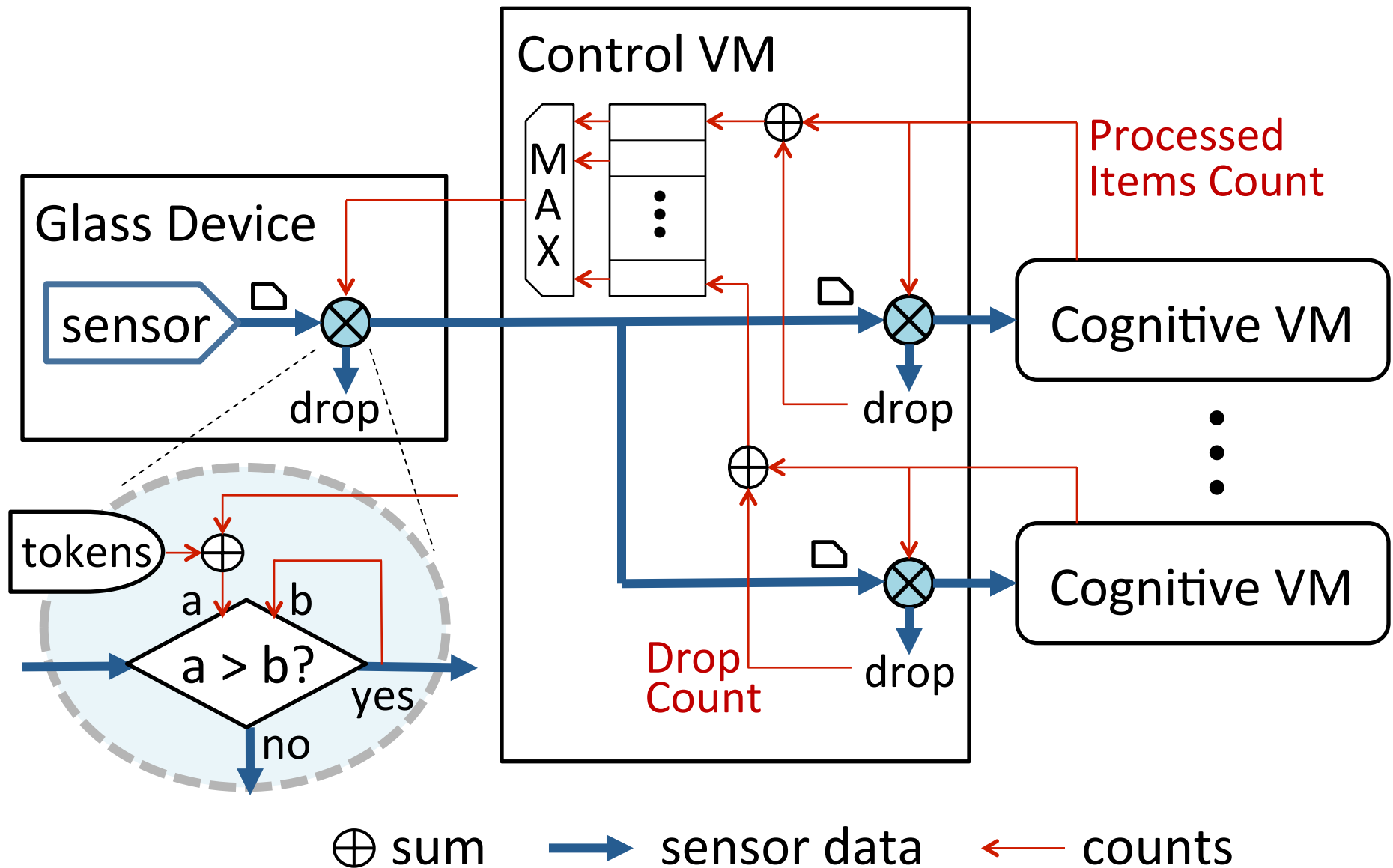
Gabriel architecture allows easy upgrade.

Exp. – Full System Performance

Cognitive Engines require different FPS

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Gabriel uses two-level token-based flow control



More in the Paper

1. Token-based flow control improves response time a lot
2. Gabriel supports multi-VM parallelism
3. Tradeoff between fidelity reduction and crisp user interaction

Conclusion & Future Work

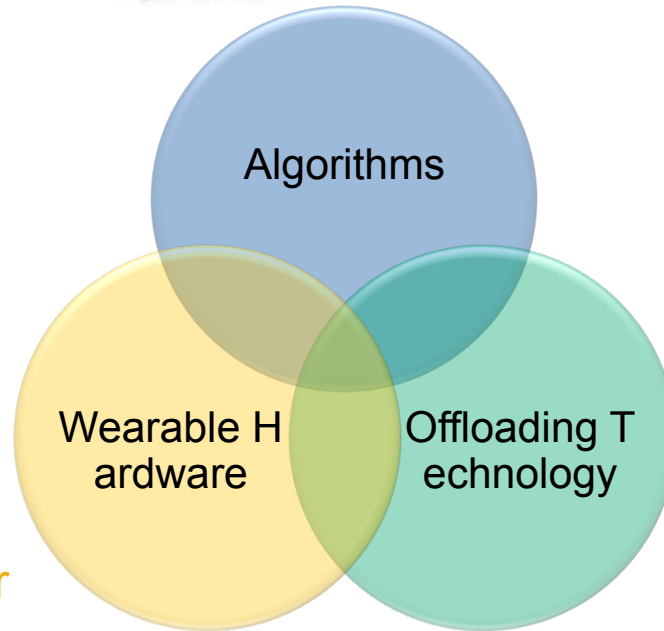
Gabriel: low-latency, flexible architecture



Speed improvement
needed

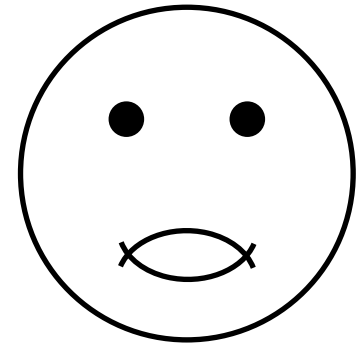


Longer battery, better
thermal dissipation



Cloudlets are helpful,
need good biz. model

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Contact: Kiryong Ha (krha@cmu.edu) Zhuo

Carnegie Mellon University Chen(zhuoc@cs.cmu.edu)

